ALGEBRA

List 6.

Change of a basis. Linear transformations: matrix, kernel, range

1. Is (1, -1, 2), (2, 1, 0), (2, 0, -1) a basis in \mathbb{R}^3 ? If yes, give the coordinates of the vector (2, 3, 4) in this basis.

2. Is (1, -1, 1), (1, 1, 0), (0, 1, 1) a basis in \mathbb{R}^3 ? If yes, give the coordinates of the vector (-2, 0, 3) in this basis.

3. Is (1, -1, 1), (1, 1, 0), (1, 0, 1) a basis in \mathbb{R}^3 ? If yes, give the coordinates of the vector (-3, 0, 2) in this basis.

4. Is (1, -1, 1), (1, 1, 0) a basis in \mathbb{R}^3 ? If yes, give the coordinates of the vector (-2, 0, 2) in this basis.

5. Is (-2, 0, 2) a linear combination of (1, -1, 1), (1, 1, 0)? If yes, with which coefficients?

6. Is (-2, 0, 1) a linear combination of (1, -1, 1), (1, 1, 0)? If yes, with which coefficients?

7. Let the linear mapping of \mathbb{R}^2 be given by T(x,y) = (2x + y, x - y). Find its matrices in the standard basis $B = \{e_1, e_2\}$ and in the basis $B' = \{v_1, v_2\}$ given by $v_1 = (1, 1), v_2 = (1, -1)$.

8. The linear mapping of \mathbb{R}^2 transforms the vector (1, 2) to (-1, 1), and the vector (2, 1) to (3, 1). Write the matrix of this mapping in the standard basis in \mathbb{R}^2 .

9. For the linear mapping of \mathbb{R}^2 which corresponds to rotation clockwise around the origin by the angle α composed with the reflection with respect to Ox axis, write the matrix of this mapping in the standard basis in \mathbb{R}^2 .

10. For the linear mapping of \mathbb{R}^2 which corresponds to reflection with respect to

- (a) the Oy axis;
- (b) the line y + x = 0;
- (c) the line 3y 4x = 0,

rite the matrices of these mappings in the standard basis in \mathbb{R}^2 .

11. For the linear mapping of \mathbb{R}^3 which corresponds to reflection with respect to

- (a) the Oz axis;
- (b) the Oyz plane;
- (c) the plane x + 2y 3z = 0,

write the matrices of these mappings in the standard basis in \mathbb{R}^3 .

12. For the linear mappings of \mathbb{R}^3 which corresponds to rotation counter-clockwise around the Oy and Oz axes by the angle α , write the matrices of these mappings in the standard basis in \mathbb{R}^3 . For which values of α these mappings commute?

13. Write the matrices in the standard basis in \mathbb{R}^3 of the rotation counter-clock wise by angle $\frac{2\pi}{3}$ around the line x = y = z.